- Let $W_{n}$ be the subspace generated by

$$
1, \sin (x), \ldots, \sin (n x), \cos (x), \ldots, \cos (n x)
$$

inside $C[0,2 \pi]$.

- Since the generators of each $W_{n}$ form an orthogonal set, they are linearly independent and it is easy to compute the projection onto $W_{n}$.
- For any $f \in C[0,2 \pi]$ we compute

$$
a_{0}=\frac{\langle f, 1\rangle}{\|1\|^{2}}, a_{k}=\frac{\langle f, \sin (k x)\rangle}{\|\sin (k x)\|^{2}} \text { and } b_{k}=\frac{\langle f, \cos (k x)\rangle}{\|\cos (k x)\|^{2}}
$$

for all $k \geq 1$.

## Main Theorem

## Theorem

If $f \in C[0,2 \pi]$ then $f(x)$ converges to

$$
a_{0}+a_{1} \sin (x)+a_{2} \sin (2 x)+\ldots+b_{1} \cos (x)+b_{2} \cos (2 x)+\ldots
$$

with respect to $\|\cdot\|$.

## Example

If $W$ is the subspace generated by

$$
1, \sin (x), \sin (2 x), \ldots, \cos (x), \cos (2 x), \ldots
$$

then by the Main Theorem, $W^{\perp}=0$. But $0^{\perp}$ is all of $C[0,2 \pi]$. $W$ is not all of $C[0,2 \pi]$ since $x \notin W$ so we have an example of $\left(W^{\perp}\right)^{\perp} \neq W$.

## Linear Transformations

## Definition

If $V$ and $W$ are vector spaces and $T: V \rightarrow W$ is a function from $V$ to $W$ then we say that $T$ is a linear transformation if for all $u, v \in V$ and scalars $c$,
(1) $T(u+v)=T(u)+T(v)$, and
(2) $T(c u)=c T(u)$.

In the case where $V=W$ and $T: V \rightarrow V$, we call $T$ a linear operator.

## Properties of Linear Transformations

## Theorem

If $T: V \rightarrow W$ is a linear transformation then
(1) $T(0)=0$
(2) $T(-v)=-T(v)$ for all $v \in V$
(3) $T(v-w)=T(v)-T(w)$ for all $v, w \in V$

## Action on a basis

## Very Important Fact

A linear transformation is completely determined by its action on a basis. That is, if $T: V \rightarrow W$ is a linear transformation and $v_{1}, v_{2}, \ldots, v_{n}$ is a basis for $V$ then, since any $v \in V$ is of the form

$$
c_{1} v_{1}+c_{2} v_{2}+\ldots+c_{n} v_{n}
$$

then

$$
T(v)=c_{1} T\left(v_{1}\right)+c_{2} T\left(v_{2}\right)+\ldots+c_{n} T\left(v_{n}\right)
$$

so $T$ is determined by the values $T\left(v_{1}\right), T\left(v_{2}\right), \ldots, T\left(v_{n}\right)$.

## Composition of Linear Transformations

## Theorem

If $U, V$ and $W$ are vector spaces and $T_{1}: U \rightarrow V$ and
$T_{2}: V \rightarrow W$ are linear transformations then the composition of $T_{2}$ with $T_{1}, T_{2} \circ T_{1}$, defined by

$$
\left(T_{2} \circ T_{1}\right)(u)=T_{2}\left(T_{1}(u)\right)
$$

is a linear transformation from $U$ to $W$.

## Kernel and Range

## Definition

If $T: V \rightarrow W$ is a linear transformation then the kernel of $T$, written $\operatorname{ker}(T)$ is the set of all $v \in V$ such that $T(v)=0$. The range of $T$, written $R(T)$, is the set of all vectors in $W$ of the form $T(v)$ for some $v \in V$.

## Theorem

If $T: V \rightarrow W$ is a linear transformation then $\operatorname{ker}(V)$ is a subspace of $V$ and $R(T)$ is a subspace of $W$.

