## Orthogonality

## Definition

- We say that two vectors $u, v \in \mathbb{R}^{n}$ are orthogonal if $u \cdot v=0$.
- We say that a set of vectors is orthogonal if any two distinct vectors in the set are orthogonal and the set is orthonormal if all the vectors have length 1.


## Orthogonality, cont'd

## Theorem (3.3.2)

If $u$ and $a$ are vectors in $n$-space and $a \neq 0$ then there are unique vectors $w_{1}$ and $w_{2}$ such that $u=w_{1}+w_{2}$ with $w_{1}$ orthogonal to $w_{2}$ and $w_{1}$ a multiple of a. In fact,

$$
w_{1}=\frac{u \cdot a}{\|a\|^{2}} a \text { and } w_{2}=u-w_{1}
$$

## Theorem (Pythagoras)

$\operatorname{In} \mathbb{R}^{n}$, if $u$ and $v$ are orthogonal then

$$
\|u\|^{2}+\|v\|^{2}=\|u+v\|^{2}
$$

## Orthogonality and matrix multiplication

- Suppose that $A$ is $m \times k$ with rows $r_{1}, \ldots, r_{m}$ and $B$ is $k \times n$ with columns $c_{1}, \ldots, c_{n}$. Then the $i j$ entry of $A B$ is $r_{i} \cdot c_{j}$.
- In particular, if $A$ is $m \times n$ and we know that $x$ satisfies $A x=0$ then $x$ is a vector in $\mathbb{R}^{n}$ which is orthogonal to all the row vectors.
- Geometrically then if $x_{0}$ satisfies $A x=b$ then all solutions of $A x=b$ can be obtained by adding $x_{0}$ to any vector which is orthogonal to all the row vectors of $A$ i.e. a solution of $A x=0$.


## Lines and planes in $\mathbb{R}^{n}$

## Definition

- If $x_{0}$ and $v$ are vectors in $\mathbb{R}^{n}$ then $x=x_{0}+t v$ defines a line passing through $x_{0}$ parallel to $v$ in $\mathbb{R}^{n}$.
- If $x_{0}, u$ and $v$ are vectors in $\mathbb{R}^{n}$ and $u$ is not a multiple of $v$ then $x=x_{0}+t_{1} u+t_{2} v$ defines the plane in $\mathbb{R}^{n}$ passing through $x_{0}$ and parallel to $u$ and $v$.


## The cross product

## Definition

Suppose that $u=\left(u_{1}, u_{2}, u_{3}\right)$ and $v=\left(v_{1}, v_{2}, v_{3}\right)$ are two vectors in $\mathbb{R}^{3}$. We define the cross product of $u$ with $v$, written $u \times v$, as

$$
\left(u_{2} v_{3}-v_{2} u_{3}, v_{1} u_{3}-u_{1} v_{3}, u_{1} v_{2}-v_{1} u_{2}\right)
$$

- $u \times v$ can also be described geometrically as a vector which is both orthogonal to $u$ and $v$, has length $\|u \mid\|\|v\| \sin (\theta)$ where $\theta$ is the angle between $u$ and $v$, and is oriented according to the right-hand rule (watch my hands).
- Theorems 3.5.1 and 3.5.2 have many properties of the cross product which follow immediately from one or the other way of looking at the cross product.

