Agenda

Chebyshev Approximation (I)

Galerkin Approach
Collocation Approach
Reciprocal Relations & Economization of Power Series

Chebyshev Approximation (II)

Spectral Differentiation
Differentiation in Real Space

Implementation of Boundary Conditions

Galerkin Approach & Basis Recombination Galerkin Approach & Tau Method Collocation Method

- Consider an approximation of $u \in L^2_\omega(I)$ in terms of a TRUNCATED CHEBYSHEV SERIES $u_N(x) = \sum_{k=0}^N \hat{u}_k T_k(x)$
- ▶ Cancel the projections of the residual $R_N = u u_N$ on the N+1 first basis function (i.e., the Chebyshev polynomials)

$$(R_N, T_I)_{\omega} = \int_{-1}^1 \left(u T_I \omega - \sum_{k=0}^N \hat{u}_k T_k T_I \omega \right) dx = 0, \quad I = 0, \dots, N$$

► Taking into account the orthogonality condition, expressions for the Chebyshev expansions coefficients are obtained

$$\hat{u}_k = \frac{2}{\pi c_k} \int_{-1}^1 u T_k \omega \, dx,$$

which can be evaluated using, e.g., the Gauss-Lobatto-Chebyshev Quadratures .

▶ QUESTION — What happens on the boundary?

Theorem

Let $P_N: L^2_\omega(I) \to \mathbb{P}_N$ be the orthogonal projection on the subspace \mathbb{P}_N of polynomials of degree $\leq N$. For all μ and σ such that $0 \leq \mu \leq \sigma$, there exists a constant C such that

$$\|u-P_{N}u\|_{\mu,\omega} < CN^{e(\mu,\sigma)}\|u\|_{\sigma,\omega}$$
 where
$$e(\mu,\sigma) = \begin{cases} 2\mu-\sigma-\frac{1}{2} & \text{for } \mu>1,\\ \\ \frac{3}{2}\mu-\sigma & \text{for } 0\leq\mu\leq1 \end{cases}$$

"Philosophy" of the proof.

- 1. First establish continuity of the mapping $u \to \tilde{u}$, where $\tilde{u}(\theta) = u(\cos(\theta))$, from the weighted Sobolev space $H^m_\omega(I)$ into the corresponding periodic Sobolev space $H^m_\rho(-\pi,\pi)$
- 2. Then leverage analogous approximation error bounds established for the case of trigonometric basis functions

- ► Consider an approximation of $u \in L^2_\omega(I)$ in terms of a truncated Chebyshev series (expansion coefficients as the unknowns) $u_N(x) = \sum_{k=0}^N \hat{u}_k T_k(x)$
- ► Cancel the residual $R_N = u u_N$ on the set of GAUSS-LOBATTO-CHEBYSHEV collocation points x_j , j = 0, ..., N (one could choose other sets of collocation points as well)

$$u(x_j) = \sum_{k=0}^{N} \hat{u}_k T_k(x_j), \quad j = 0, \dots, N$$

Noting that $T_k(x_j) = \cos\left(k\cos^{-1}(\cos(\frac{j\pi}{N}))\right) = \cos(k\frac{j\pi}{N})$ and denoting $u_j \triangleq u(x_j)$ we obtain

$$u_j = \sum_{k=0}^{N} \hat{u}_k \cos\left(k\frac{\pi j}{N}\right), \quad j = 0, \dots, N$$

The above system of equations can be written as $U = \mathcal{T}\hat{U}$, where U and \hat{U} are vectors of grid values and expansion coefficients, respectively.

In fact, the matrix \mathcal{T} is invertible and

$$[\mathcal{T}^{-1}]_{jk} = \frac{2}{\overline{c}_j \overline{c}_k N} \cos\left(\frac{k\pi j}{N}\right), \quad j, k = 0, \dots, N$$

Consequently, the expansion coefficients can be expressed as follows

$$\hat{u}_k = \frac{2}{\overline{c}_k N} \sum_{j=0}^N \frac{1}{\overline{c}_j} u_j \cos\left(\frac{k\pi j}{N}\right) = \frac{2}{\overline{c}_k N} \sum_{j=0}^N \frac{1}{\overline{c}_j} u_j \Re\left[e^{i\left(\frac{k\pi j}{N}\right)}\right], \quad k = 0, \dots, N$$

Note that this expression is nothing else than the COSINE TRANSFORM of U which can be very efficiently evaluated using a COSINE FFT

- ▶ The same expression can be obtained by
 - ▶ multiplying each side of $u_j = \sum_{k=0}^{N} \hat{u}_k T_k(x_j)$ by $\frac{T_i(x_j)}{\overline{c}_i}$
 - summing the resulting expression from j = 0 to j = N
 - ▶ using the DISCRETE ORTHOGONALITY RELATION

$$\frac{\pi}{N} \sum_{j=0}^{N} \frac{1}{\overline{c}_i} T_k(\tilde{\xi}_j) T_l(\tilde{\xi}_j) = \frac{\pi \overline{c}_k}{2} \delta_{kl}$$

► Note that the expression for the DISCRETE CHEBYSHEV
TRANSFORM

$$\hat{u}_k = \frac{2}{\overline{c}_k N} \sum_{j=0}^N \frac{1}{\overline{c}_j} u_j \cos\left(\frac{k\pi j}{N}\right), \quad k = 0, \dots, N$$

can also be obtained by using the Gauss-Lobatto-Chebyshev quadrature to approximate the continuous expressions

$$\hat{u}_k = \frac{2}{\pi c_k} \int_{-1}^1 u T_k \omega \, dx, \quad k = 0, \dots, N,$$

Such an approximation is **EXACT** for $u \in \mathbb{P}_N$

- ► Analogous expressions for the Discrete Chebyshev Transforms can be derived for other set of collocation points (Gauss, Gauss-Radau)
- ► Note similarities with respect to the case periodic functions and the Discrete Fourier Transform

- ► As was the case with Fourier spectral methods, there is a very close connection between COLLOCATION-BASED INTERPOLATION and GALERKIN APPROXIMATION
- ▶ DISCRETE CHEBYSHEV TRANSFORM can be associated with an INTERPOLATION OPERATOR $P_C: C^0(I) \to \mathbb{R}^N$ defined such that $(P_C u)(x_j) = u(x_j), j = 0, ..., N$ (where x_j are the Gauss-Lobatto collocation points)

Theorem

Let $s>\frac{1}{2}$ and σ be given and $0\leq\sigma\leq s$. There exists a constant C such that

$$||u - P_C u||_{\sigma,\omega} < CN^{2\sigma-s}||u||_{s,\omega}$$

for all $u \in H^s_{\omega}(I)$.

Outline of the Proof.

Changing the variables to $\tilde{u}(\theta) = u(\cos(\theta))$ we convert this problem to a problem already analyzed in the context of the Fourier interpolation for periodic functions

► Relation between the GALERKIN and COLLOCATION coefficients, i.e.,

$$\hat{u}_{k}^{e} = \frac{2}{\pi c_{k}} \int_{-1}^{1} u(x) T_{k}(x) \omega(x) dx, \qquad k = 0, \dots, N$$

$$\hat{\mathbf{u}}_{k}^{c} = \frac{2}{\overline{c}_{k} N} \sum_{j=0}^{N} \frac{1}{\overline{c}_{j}} u_{j} \cos \left(\frac{k \pi j}{N} \right), \qquad k = 0, \dots, N$$

▶ Using the representation $u(x) = \sum_{l=0}^{\infty} \hat{u}_l^e T_l(x)$ in the latter expression and invoking the discrete orthogonality relation we obtain

$$\begin{split} \hat{u}_k^c &= \frac{2}{\overline{c}_k N} \sum_{l=0}^N \hat{u}_l^e \left[\sum_{j=0}^N \frac{1}{\overline{c}_j} T_k(x_j) T_l(x_j) \right] + \frac{2}{\overline{c}_k N} \sum_{l=N+1}^\infty \hat{u}_l^e \left[\sum_{j=0}^N \frac{1}{\overline{c}_j} T_k(x_j) T_l(x_j) \right], \\ &= \hat{u}_k^e \\ &\quad + \frac{2}{\overline{c}_k N} \sum_{l=N+1}^\infty \hat{u}_l^e C_{kl} \\ \text{where} \quad C_{kl} &= \sum_{j=0}^N \frac{1}{\overline{c}_j} T_k(x_j) T_l(x_j) = \sum_{j=0}^N \frac{1}{\overline{c}_j} \cos\left(\frac{kj\pi}{N}\right) \cos\left(\frac{lj\pi}{N}\right) \\ &= \frac{1}{2} \sum_{l=0}^N \frac{1}{\overline{c}_j} \left[\cos\left(\frac{k-l}{N}j\pi\right) + \cos\left(\frac{k+l}{N}j\pi\right) \right] \end{split}$$

Using the identity

$$\sum_{j=0}^{N} \cos\left(\frac{pi\pi}{N}\right) = \begin{cases} N+1, & \text{if } p = 2mN, \ m = 0, \pm 1, \pm 2, \dots \\ \frac{1}{2}[1+(-1)^{p}] & \text{otherwise} \end{cases}$$

we can calculate C_{kl} which allows us to express the relation between the Galerkin and collocation coefficients as follows

$$\hat{u}_{k}^{c} = \hat{u}_{k}^{e} + \frac{1}{\overline{c}_{k}} \left[\sum_{\substack{m=1\\2mN > N-k}}^{\infty} \hat{u}_{k+2mN}^{e} + \sum_{\substack{m=1\\2mN > N+k}}^{\infty} \hat{u}_{-k+2mN}^{e} \right]$$

- ► The terms in square brackets represent the ALIASING ERRORS .

 Their origin is precisely the same as in the Fourier (pseudo)-spectral method.
- ► Aliasing errors can be removed using the 3/2 APPROACH in the same way as in the Fourier (pseudo)-spectral method

 \triangleright expressing the first N Chebyshev polynomials as functions of x^k ,

$$k = 1, ..., N$$
 $T_0(x) = 1,$
 $T_1(x) = x,$
 $T_2(x) = 2x^2 - 1,$
 $T_3(x) = 4x^3 - 3x,$
 $T_4(x) = 8x^4 - 8x^2 + 1$

which can be written as $V = \mathbb{K}X$, where $[V]_k = T_k(x)$, $[X]_k = x^k$, and \mathbb{K} is a LOWER-TRIANGULAR matrix

Solving this system (trivially!) results in the following RECIPROCAL RELATIONS $1 = T_0(x)$,

$$x = T_1(x),$$

$$x^2 = \frac{1}{2}[T_0(x) + T_2(x)],$$

$$x^3 = \frac{1}{4}[3T_1(x) + T_3(x)],$$

$$x^4 = \frac{1}{8}[3T_0(x) + 4T_2(x) + T_4(x)]$$

- Find the best polynomial approximation of order 3 of $f(x) = e^x$ on [-1, 1]
- Construct the (Maclaurin) expansion

$$e^x = 1 + x + \frac{1}{2}x^2 + \frac{1}{6}x^3 + \frac{1}{24}x^4 + \dots$$

► Rewrite the expansion in terms of CHEBYSHEV POLYNOMIALS using the reciprocal relations

$$e^{x} = \frac{81}{64}T_{0}(x) + \frac{9}{8}T_{1}(x) + \frac{13}{48}T_{2}(x) + \frac{1}{24}T_{3}(x) + \frac{1}{192}T_{4}(x) + \dots$$

- ▶ Truncate this expansion to the 3^{rd} order and translate the expansion back to the x^k representation
- ► Truncation error is given by the magnitude of the first truncated term; Note that the CHEBYSHEV EXPANSION COEFFICIENTS are much smaller than the corresponding TAYLOR EXPANSION COEFFICIENTS!
- ▶ How is it possible the same number of expansion terms, but higher accuracy?

- ▶ Assume function approximation in the form $u_N(x) = \sum_{k=0}^N \hat{u}_k T_k(x)$
- ▶ First, note that CHEBYSHEV PROJECTION and DIFFERENTIATION do not commute, i.e., $P_N(\frac{du}{dx}) \neq \frac{d}{dx}(P_N u)$
- ▶ Sequentially applying the recurrence relation $2T_k = \frac{T'_{k+1}}{k+1} \frac{T'_{k-1}}{k-1}$ we obtain

$$T'_{k}(x) = 2k \sum_{p=0}^{K} \frac{1}{c_{k-1-2p}} T_{k-1-2p}(x), \text{ where } K = \left[\frac{k-1}{2}\right]$$

Consider the first derivative

$$u'_N(x) = \sum_{k=0}^N \hat{u}_k T'_k(x) = \sum_{k=0}^N \hat{u}_k^{(1)} T_k(x)$$

where, using the above expression for $T'_k(x)$, we obtain the expansion coefficients as

$$\hat{u}_k^{(1)} = \frac{2}{c_k} \sum_{\substack{p=k+1 \ (p+k) \text{ odd}}}^{N} p \hat{u}_p, \quad k = 0, \dots, N-1, \quad \text{and} \quad \hat{u}_N^{(1)} = 0$$

► Spectral differentiation (with the expansion coefficients as unknowns) can thus be written as

$$\hat{U}^{(1)} = \hat{\mathbb{D}}\hat{U},$$

where $\hat{U} = [\hat{u}_0 \dots, \hat{u}_N]^T$, $\hat{U}^{(1)} = [\hat{u}_0^{(1)} \dots, \hat{u}_N^{(1)}]^T$, and $\hat{\mathbb{D}}$ is an UPPER-TRIANGULAR matrix with entries deduced based on the previous expression

For the second derivative one obtains similarly

$$u_N''(x) = \sum_{k=0}^N \hat{u}_k^{(2)} T_k(x)$$

$$\hat{u}_k^{(2)} = \frac{1}{c_k} \sum_{\substack{p=k+2\\ (p+k) \text{ even}}}^N p(p^2 - k^2) \hat{u}_p, \quad k = 0, \dots, N-2$$

and
$$\hat{u}_{N}^{(2)} = \hat{u}_{N-1}^{(2)} = 0$$

► QUESTION — What is the structure of the second-order differentiation matrix?

Assume the function u(x) is approximated in terms of its nodal values, i.e.,

$$u(x) \cong u_N(x) = \sum_{j=0}^N u(x_j) C_j(x),$$

where $\{x_j\}$ are the Gauss-Lobatto-Chebyshev points and $C_j(x)$ are the associated Cardinal Functions

$$C_j(x) = (-1)^{j+1} \frac{(1-x^2)}{c_j N^2(x-x_j)} \frac{dT_N(x)}{dx} = \frac{2}{Np_j} \sum_{m=0}^{N} \frac{1}{p_m} T_m(x_j) T_m(x),$$

where

$$p_j = \left\{ egin{array}{ll} 2 & \qquad & ext{for } j=0,N, \ 1 & \qquad & ext{for } j=1,\ldots,N-1 \end{array}
ight., \qquad \qquad c_j = \left\{ egin{array}{ll} 2 & \qquad & ext{for } j=N, \ 1 & \qquad & ext{for } j=0,\ldots,N-1 \end{array}
ight.$$

▶ The DIFFERENTIATION MATRIX $\mathbb{D}^{(p)}$ relating the nodal values of the p-th derivative $u_N^{(p)}$ to the nodal values of u is obtained by differentiating the cardinal function appropriate number of times

$$u_N^{(p)}(x_j) = \sum_{k=0}^N \frac{d^{(p)}C_k(x_j)}{dx^{(p)}} u(x_k) = \sum_{k=0}^N d_{jk}^{(p)} u(x_k), \quad j = 0, \dots, N$$

Expressions for the entries of the DIFFERENTIATION MATRIX $d_{jk}^{(1)}$ at the the Gauss-Lobatto-Chebyshev collocation points

$$d_{jk}^{(1)} = \frac{\overline{c}_j}{\overline{c}_k} \frac{(-1)^{j+k}}{x_j - x_k}, \qquad 0 \le j, k \le N, \ j \ne k,$$

$$d_{jj}^{(1)} = -\frac{x_j}{2(1 - x_j^2)}, \qquad 1 \le j \le N - 1,$$

$$d_{00}^{(1)} = -d_{NN}^{(1)} = \frac{2N^2 + 1}{6},$$

► Thus in the matrix (operator) notation

$$U^{(1)}=\mathbb{D}U$$

Note that Rows of the differentiation matrix

are in fact equivalent to N-th order asymmetric finite-difference formulas on a nonuniform grid; in other words, spectral differentiation using nodal values as unknowns is equivalent to finite differences employing ALL N GRID POINTS AVAILABLE.

Expressions for the entries of Second-Order Differentiation Matrix $d_{jk}^{(2)}$ at the the Gauss-Lobatto-Chebyshev collocation points $(U^{(2)} = \mathbb{D}^{(2)}U)$

$$\begin{split} d_{jk}^{(2)} &= \frac{(-1)^{j+k}}{\overline{c}_k} \frac{x_j^2 + x_j x_k - 2}{(1 - x_j^2)(x_j - x_k)^2}, & 1 \leq j \leq N-1, \ 0 \leq k \leq N, \ j \neq k \\ d_{jj}^{(2)} &= -\frac{(N^2 - 1)(1 - x_j^2) + 3}{3(1 - x_j^2)^2}, & 1 \leq j \leq N-1, \\ d_{0k}^{(2)} &= \frac{2}{3} \frac{(-1)^k}{\overline{c}_k} \frac{(2N^2 + 1)(1 - x_k) - 6}{(1 - x_k)^2}, & 1 \leq k \leq N \\ d_{Nk}^{(2)} &= \frac{2}{3} \frac{(-1)^{N+k}}{\overline{c}_k} \frac{(2N^2 + 1)(1 + x_k) - 6}{(1 + x_k)^2}, & 0 \leq k \leq N-1 \\ d_{00}^{(2)} &= d_{NN}^{(2)} = \frac{N^4 - 1}{15}, & 0 \leq k \leq N-1 \end{split}$$

► Note that

- $d_{jk}^{(2)} = \sum_{p=0}^{N} d_{jp}^{(1)} d_{pk}^{(1)}$
- ▶ Interestingly, \mathbb{D}^2 is not a SYMMETRIC MATRIX ...

► Consider an ELLIPTIC BOUNDARY VALUE PROBLEM (BVP) :

$$\begin{split} &-\nu u''+au'+bu=f, &&\text{in } [-1,1]\\ &\alpha_- u+\beta_- u'=g_- &&x=-1\\ &\alpha_+ u+\beta_+ u'=g_+ &&x=1 \end{split}$$

- Chebyshev polynomials do not satisfy homogeneous boundary conditions, hence standard Galerkin approach is not directly applicable.
- ► Basis Recombination:
 - Convert the BVP to the corresponding form with HOMOGENEOUS BOUNDARY CONDITIONS
 - ► Take linear combinations of Chebyshev polynomials to construct a new basis satisfying HOMOGENEOUS DIRICHLET BOUNDARY CONDITIONS

$$\varphi_k(\pm 1) = 0$$

$$\varphi_k(x) = \begin{cases} T_k(x) - T_0(x) = T_k - 1, & k - \text{even} \\ T_k(x) - T_1(x), & k - \text{odd} \end{cases}$$

Note that the new basis preserves orthogonality

- ► THE TAU METHOD (Lanczos, 1938) consists in using a Galerkin approach in which explicit enforcement of the boundary conditions replaces projections on some of the test functions
- Consider the residual

$$R_N(x) = -\nu u_N'' + au_N' + bu_N - f,$$

where $u_N(x) = \sum_{k=0}^N \hat{u}_k T_k(x)$

▶ Cancel projections of the residual on the first N-2 basis functions

$$(R_N, T_I)_{\omega} = \sum_{k=0}^{N} \left(-\nu \hat{u}_k^{(2)} + a \hat{u}_k^{(1)} + b \hat{u}_k \right) \int_{-1}^{1} T_k T_I \omega \, dx - \int_{-1}^{1} f T_I \omega \, dx, \quad I = 0, \dots, \frac{N-2}{N-2}$$

▶ Thus, using orthogonality, we obtain

$$-\nu \hat{u}_{k}^{(2)} + a\hat{u}_{k}^{(1)} + b\hat{u}_{k} = \hat{f}_{k}, \quad k = 0, \dots, N-2$$

where
$$\hat{f}_k = \int_{-1}^1 f T_k \omega dx$$

Noting that $T_k(\pm 1) = (\pm 1)^k$ and $T_k'(\pm 1) = (\pm 1)^{k+1}k^2$, the BOUNDARY CONDITIONS are enforced by supplementing the residual equations with

$$\sum_{k=0}^{N} (-1)^{k} (\alpha_{-} - \beta_{-} k^{2}) \hat{u}_{k} = g_{-}$$

$$\sum_{k=0}^{N} (-1)^{k} (\alpha_{+} + \beta_{+} k^{2}) \hat{u}_{k} = g_{+}$$

Expressing $\hat{u}_k^{(2)}$ and $\hat{u}_k^{(1)}$ in terms of \hat{u}_k via the Chebyshev spectral differentiation matrices we obtain the following system

$$\mathbb{A}\hat{U} = \hat{F}$$

where $\hat{U} = [\hat{u}_0, \dots, \hat{u}_N]^T$, $F = [\hat{f}_0, \dots, \hat{f}_{N-2}, \mathbf{g}_-, \mathbf{g}_+]$ and the matrix \mathbb{A} is obtained by adding the two rows representing the boundary conditions (see above) to the matrix $\mathbb{A}_1 = -\nu \hat{\mathbb{D}}^2 + a\hat{\mathbb{D}} + bI$.

▶ When the domain boundary is not just a point (e.g., in 2D / 3D), formulation of the Tau method becomes somewhat more involved

► Consider the residual

$$R_N(x) = -\nu u_N'' + au_N' + bu_N - f,$$

where
$$u_N(x) = \sum_{k=0}^N \hat{u}_k T_k(x)$$

▶ Cancel this residual at N-1 GAUSS-LOBATTO-CHEBYSHEV collocation points located in the interior of the domain

$$-\nu u_N''(x_j) + au_N'(x_j) + bu_N(x_j) = f(x_j), \quad j = 1, \dots, N-1$$

Enforce the two boundary conditions at endpoints

$$\alpha_{-}u_{N}(x_{N}) + \beta_{-}u'_{N}(x_{N}) = g_{-}$$

 $\alpha_{+}u_{N}(x_{0}) + \beta_{+}u'_{N}(x_{0}) = g_{-}$

Note that this shows the utility of using the GAUSS-LOBATTO-CHEBYSHEV collocation points

 \triangleright Consequently, the following system of N+1 equations is obtained

$$\begin{split} \sum_{k=0}^{N} (-\nu d_{jk}^{(2)} + a d_{jk}^{(1)}) u_N(x_j) + b u_N(x_j) &= f(x_j), \quad j = 1, \dots, N-1 \\ \alpha_- u_N(x_N) + \beta_- \sum_{k=0}^{N} d_{Nk}^{(1)} u_N(x_k) &= g_- \\ \alpha_+ u_N(x_0) + \beta_+ \sum_{k=0}^{N} d_{0k}^{(1)} u_N(x_k) &= g_+ \end{split}$$

which can be written as $\mathbb{A}_c U = F$, where $[\mathbb{A}_c]_{jk} = [\mathbb{A}_{c0}]_{jk}$, $j,k=1,\ldots,N-1$ with \mathbb{A}_{c0} given by

$$\mathbb{A}_{c0} = (-\nu \mathbb{D}^2 + a\mathbb{D} + b\mathbb{I})U$$

and the BOUNDARY CONDITIONS above added as the rows 0 and N of \mathbb{A}_{c}

▶ Note that the matrix corresponding to this system of equations may be POORLY CONDITIONED , so special care must be exercised when solving this system for large *N*.

▶ Similar approach can be used when the nodal values $u(x_j)$, rather than the Chebyshev coefficients \hat{u}_k are unknowns

- ► When the equation has NONCONSTANT COEFFICIENTS, similar difficulties as in the Fourier case are encountered (evaluation of CONVOLUTION SUMS)
- ► Consequently, the COLLOCATION (pseudo-spectral) approach is preferable along the guidelines laid out in the case of the Fourier spectral methods
- Assuming a = a(x) in the elliptic boundary value problem, we need to make the following modification to \mathbb{A}_c :

$$\mathbb{A}'_{c0} = (-\nu \mathbb{D}^2 + \mathbb{D}' + b\mathbb{I})U,$$

where
$$\mathbb{D}' = [a(x_j)d_{jk}^{(1)}], j, k = 1, ..., N$$

For the Burgers equation $\partial_t u + \frac{1}{2} \partial_x u^2 - \nu \partial_x^2 u$ we obtain at every time step n

$$(\mathbb{I} - \Delta t \,\nu\,\mathbb{D}^{(2)})U^{n+1} = U^n - \frac{1}{2}\Delta t\,\mathbb{D}\,W^n,$$

where $[W^n]_j = [U^n]_j [U^n]_j$; Note that an algebraic system has to be solved at each time step

Epilogue — Domain Decomposition

- Motivation:
 - ► treatment of problem in IRREGULAR DOMAINS
 - ► STIFF PROBLEMS
- ▶ PHILOSOPHY partition the original domain Ω into a number of SUBDOMAINS $\{\Omega_m\}_{m=1}^M$ and solve the problem separately on each those while respecting consistency conditions on the interfaces
- Spectral Element Method
 - lacktriangle consider a collection of problems posed on each subdomain Ω_m

$$\mathcal{L}u_m = f$$

 $u_{m-1}(a_m) = u_m(a_m), \qquad u_m(a_{m+1}) = u_{m+1}(a_{m+1})$

- ▶ Transform each subdomain Ω_m to I = [-1, 1]
- use a separate set of N_m ORTHOGONAL POLYNOMIALS to approximate the solution on every subinterval
- boundary conditions on interfaces provide coupling between problems on subdomains