# Agenda

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- ► Consider an approximation of  $u \in L^2_{\omega}(I)$  in terms of a TRUNCATED CHEBYSHEV SERIES  $u_N(x) = \sum_{k=0}^{N} \hat{u}_k \, T_k(x)$
- ► Cancel the projections of the residual  $R_N = u u_N$  on the  $N + 1$  first basis function (i.e., the Chebyshev polynomials)

$$
(R_N, T_I)_{\omega} = \int_{-1}^1 \left( u T_I \omega - \sum_{k=0}^N \hat{u}_k T_k T_I \omega \right) dx = 0, \quad I = 0, \ldots, N
$$

 $\blacktriangleright$  Taking into account the orthogonality condition, expressions for the Chebyshev expansions coefficients are obtained

<span id="page-1-0"></span>
$$
\hat{u}_k = \frac{2}{\pi c_k} \int_{-1}^1 u T_k \omega \, dx,
$$

which can be evaluated using, e.g., the GAUSS-LOBATTO-CHEBYSHEV QUADRATURES.

 $\Omega$ UESTION — What happens on the boundary?

#### Theorem

Let  $P_N$  :  $L^2_\omega(I)\to \mathbb{P}_N$  be the orthogonal projection on the subspace  $\mathbb{P}_N$  of polynomials of degree  $\leq N$ . For all  $\mu$  and  $\sigma$  such that  $0 \leq \mu \leq \sigma$ , there exists a constant C such that

$$
||u - P_N u||_{\mu,\omega} < CN^{e(\mu,\sigma)} ||u||_{\sigma,\omega}
$$
  
where 
$$
e(\mu,\sigma) = \begin{cases} 2\mu - \sigma - \frac{1}{2} & \text{for } \mu > 1, \\ \frac{3}{2}\mu - \sigma & \text{for } 0 \le \mu \le 1 \end{cases}
$$

- "Philosophy" of the proof.
	- 1. First establish continuity of the mapping  $u \to \tilde{u}$ , where  $\tilde{u}(\theta) = u(\cos(\theta))$ , from the weighted Sobolev space  $H_\omega^m(I)$  into the corresponding periodic Sobolev space  $H_p^m(-\pi,\pi)$
	- 2. Then leverage analogous approximation error bounds established for the case of trigonometric basis functions

- ► Consider an approximation of  $u \in L^2_{\omega}(I)$  in terms of a truncated Chebyshev series (expansion coefficients as the unknowns)  $u_N(x) = \sum_{k=0}^N \hat{u}_k \, T_k(x)$
- ► Cancel the residual  $R_N = u u_N$  on the set of GAUSS-LOBATTO-CHEBYSHEV collocation points  $x_j$ ,  $j = 0, ..., N$ (one could choose other sets of collocation points as well)

$$
u(x_j) = \sum_{k=0}^N \hat{u}_k T_k(x_j), \quad j=0,\ldots,N
$$

► Noting that  $T_k(x_j) = \cos\left(k \cos^{-1}(\cos(\frac{j\pi}{N}))\right) = \cos(k\frac{j\pi}{N})$  $\frac{1}{N}$ ) and denoting  $u_i \triangleq u(x_i)$  we obtain  $u_j = \sum_{k=1}^{N} \hat{u}_k \cos\left(k \frac{\pi j}{N}\right)$ N  $\bigg), \ \ j=0,\ldots,N$ 

<span id="page-3-0"></span> $k=0$ 

 $\blacktriangleright$  The above system of equations can be written as  $U = \mathcal{T} \hat{U}$ , where  $U$ and  $\hat{U}$  are vectors of grid values and expansion coefficients, respectively.

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In fact, the matrix  $T$  is invertible and

$$
[\mathcal{T}^{-1}]_{jk} = \frac{2}{\overline{c}_j \overline{c}_k N} \cos\left(\frac{k\pi j}{N}\right), \quad j, k = 0, \ldots, N
$$

 $\triangleright$  Consequently, the expansion coefficients can be expressed as follows

$$
\hat{u}_k = \frac{2}{\overline{c}_k N} \sum_{j=0}^N \frac{1}{\overline{c}_j} u_j \cos\left(\frac{k\pi j}{N}\right) = \frac{2}{\overline{c}_k N} \sum_{j=0}^N \frac{1}{\overline{c}_j} u_j \Re\left[e^{i\left(\frac{k\pi j}{N}\right)}\right], \quad k = 0, \ldots, N
$$

Note that this expression is nothing else than the COSINE TRANSFORM of U which can be very efficiently evaluated using a cosine FFT

 $\blacktriangleright$  The same expression can be obtained by

- $\blacktriangleright$  multiplying each side of  $u_j = \sum_{k=0}^N \hat{u}_k \, T_k(x_j)$  by  $\frac{T_l(x_j)}{\overline{c}_j}$
- In summing the resulting expression from  $j = 0$  to  $j = N$
- $\triangleright$  using the DISCRETE ORTHOGONALITY RELATION

$$
\frac{\pi}{N}\sum_{j=0}^N\frac{1}{\bar{c}_j}\mathcal{T}_k(\tilde{\xi}_j)\mathcal{T}_l(\tilde{\xi}_j)=\frac{\pi\bar{c}_k}{2}\delta_{kl}
$$

 $\triangleright$  Note that the expression for the DISCRETE CHEBYSHEV **TRANSFORM** 

$$
\hat{u}_k = \frac{2}{\overline{c}_k N} \sum_{j=0}^N \frac{1}{\overline{c}_j} u_j \cos\left(\frac{k\pi j}{N}\right), \quad k = 0, \ldots, N
$$

can also be obtained by using the Gauss-Lobatto-Chebyshev quadrature to approximate the continuous expressions

$$
\hat{u}_k=\frac{2}{\pi c_k}\int_{-1}^1 u T_k \omega \,dx, \quad k=0,\ldots,N,
$$

Such an approximation is EXACT for  $u \in \mathbb{P}_N$ 

- $\triangleright$  Analogous expressions for the Discrete Chebyshev Transforms can be derived for other set of collocation points (Gauss, Gauss-Radau)
- $\triangleright$  Note similarities with respect to the case periodic functions and the Discrete Fourier Transform
- $\triangleright$  As was the case with Fourier spectral methods, there is a very close connection between collocation-based interpolation and GALERKIN APPROXIMATION
- $\triangleright$  DISCRETE CHEBYSHEV TRANSFORM can be associated with an INTERPOLATION OPERATOR  $P_\mathcal{C} : \mathcal{C}^0(I) \rightarrow \mathbb{R}^N$  defined such that  $(P<sub>C</sub> u)(x<sub>i</sub>) = u(x<sub>i</sub>), i = 0,..., N$  (where x<sub>i</sub> are the Gauss-Lobatto collocation points)

#### **Theorem**

Let  $s>\frac{1}{2}$  $\frac{1}{2}$  and  $\sigma$  be given and  $0 \leq \sigma \leq s$ . There exists a constant C such that

$$
||u - P_C u||_{\sigma,\omega} < C N^{2\sigma - s} ||u||_{s,\omega}
$$

for all  $u \in H^s_\omega(I)$ .

### Outline of the Proof.

Changing the variables to  $\tilde{u}(\theta) = u(\cos(\theta))$  we convert this problem to a problem already analyzed in the context of the Fourier interpolation for periodic functions

 $\triangleright$  Relation between the GALERKIN and COLLOCATION coefficients, i.e.,

$$
\hat{u}_k^e = \frac{2}{\pi c_k} \int_{-1}^1 u(x) \, T_k(x) \omega(x) \, dx, \qquad k = 0, \dots, N
$$
  

$$
\hat{u}_k^c = \frac{2}{\overline{c}_k N} \sum_{j=0}^N \frac{1}{\overline{c}_j} u_j \cos\left(\frac{k\pi j}{N}\right), \qquad k = 0, \dots, N
$$

► Using the representation  $u(x) = \sum_{l=0}^{\infty} \hat{u}_l^e T_l(x)$  in the latter expression and invoking the discrete orthogonality relation we obtain

$$
\hat{u}_{k}^{c} = \frac{2}{\overline{c}_{k}N} \sum_{l=0}^{N} \hat{u}_{l}^{e} \left[ \sum_{j=0}^{N} \frac{1}{\overline{c}_{j}} T_{k}(x_{j}) T_{l}(x_{j}) \right] + \frac{2}{\overline{c}_{k}N} \sum_{l=N+1}^{\infty} \hat{u}_{l}^{e} \left[ \sum_{j=0}^{N} \frac{1}{\overline{c}_{j}} T_{k}(x_{j}) T_{l}(x_{j}) \right],
$$
\n
$$
= \hat{u}_{k}^{e} + \frac{2}{\overline{c}_{k}N} \sum_{l=N+1}^{\infty} \hat{u}_{l}^{e} C_{kl}
$$
\nwhere  $C_{kl} = \sum_{j=0}^{N} \frac{1}{\overline{c}_{j}} T_{k}(x_{j}) T_{l}(x_{j}) = \sum_{j=0}^{N} \frac{1}{\overline{c}_{j}} \cos\left(\frac{kj\pi}{N}\right) \cos\left(\frac{lj\pi}{N}\right)$ \n
$$
= \frac{1}{2} \sum_{j=0}^{N} \frac{1}{\overline{c}_{j}} \left[ \cos\left(\frac{k-l}{N}j\pi\right) + \cos\left(\frac{k+l}{N}j\pi\right) \right]
$$
\n**B. Protas MATH745, Fall 2018**

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#### $\triangleright$  Using the identity

$$
\sum_{j=0}^N \cos\left( \frac{pi\pi}{N}\right) = \left\{\frac{N+1}{\frac{1}{2}[1+(-1)^p]} \right.
$$

$$
N + 1
$$
, if  $p = 2mN$ ,  $m = 0, \pm 1, \pm 2,...$ 

otherwise

we can calculate  $C_{kl}$  which allows us to express the relation between the Galerkin and collocation coefficients as follows

$$
\hat{u}_k^c = \hat{u}_k^e + \frac{1}{\overline{c}_k} \left[ \sum_{\substack{m=1 \ 2mN > N-k}}^{\infty} \hat{u}_{k+2mN}^e + \sum_{\substack{m=1 \ 2mN > N+k}}^{\infty} \hat{u}_{-k+2mN}^e \right]
$$

- $\triangleright$  The terms in square brackets represent the ALIASING ERRORS. Their origin is precisely the same as in the Fourier (pseudo)-spectral method.
- $\triangleright$  Aliasing errors can be removed using the  $3/2$  APPROACH in the same way as in the Fourier (pseudo)-spectral method

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 $\blacktriangleright$  expressing the first N Chebyshev polynomials as functions of  $x^k$ ,

 $k = 1, \ldots, N$   $T_0(x) = 1,$  $T_1(x) = x$ ,  $T_2(x) = 2x^2 - 1$ ,  $T_3(x) = 4x^3 - 3x,$  $T_4(x) = 8x^4 - 8x^2 + 1$ 

which can be written as  $\;\; V = \mathbb{K} X$  , where  $[V]_k = T_k(x)$ ,  $[X]_k = x^k$ , and  $K$  is a LOWER-TRIANGULAR matrix

 $\triangleright$  Solving this system (trivially!) results in the following RECIPROCAL RELATIONS  $1 = T_0(x)$ ,

<span id="page-9-0"></span>
$$
x = T_1(x),
$$
  
\n
$$
x^2 = \frac{1}{2}[T_0(x) + T_2(x)],
$$
  
\n
$$
x^3 = \frac{1}{4}[3T_1(x) + T_3(x)],
$$
  
\n
$$
x^4 = \frac{1}{8}[3T_0(x) + 4T_2(x) + T_4(x)]
$$
  
\nB. Prots  
\nMATHT45, Fall 2018

- ► Find the best polynomial approximation of order 3 of  $f(x) = e^x$  on  $[-1,1]$
- Construct the (Maclaurin) expansion

$$
e^x = 1 + x + \frac{1}{2}x^2 + \frac{1}{6}x^3 + \frac{1}{24}x^4 + \dots
$$

 $\triangleright$  Rewrite the expansion in terms of CHEBYSHEV POLYNOMIALS using the reciprocal relations

$$
e^{x} = \frac{81}{64}T_0(x) + \frac{9}{8}T_1(x) + \frac{13}{48}T_2(x) + \frac{1}{24}T_3(x) + \frac{1}{192}T_4(x) + \dots
$$

- **F** Truncate this expansion to the 3<sup>rd</sup> order and translate the expansion back to the  $x^k$  representation
- $\blacktriangleright$  Truncation error is given by the magnitude of the first truncated term; Note that the CHEBYSHEV EXPANSION COEFFICIENTS are much smaller than the corresponding TAYLOR EXPANSION COEFFICIENTS !
- $\blacktriangleright$  How is it possible the same number of expansion terms, but higher accuracy?

- Assume function approximation in the form  $u_N(x) = \sum_{k=0}^N \hat{u}_k \, T_k(x)$
- First, note that CHEBYSHEV PROJECTION and DIFFERENTIATION do not commute, i.e.,  $P_N(\frac{du}{dx}) \neq \frac{d}{dx}(P_N u)$
- ► Sequentially applying the recurrence relation  $2\,T_k = \frac{T'_{k+1}}{k+1} \frac{T'_{k-1}}{k-1}$  we obtain

$$
T'_{k}(x) = 2k \sum_{p=0}^{K} \frac{1}{c_{k-1-2p}} T_{k-1-2p}(x), \text{ where } K = \left[\frac{k-1}{2}\right]
$$

 $\blacktriangleright$  Consider the first derivative

<span id="page-11-0"></span>
$$
u'_{N}(x) = \sum_{k=0}^{N} \hat{u}_{k} T'_{k}(x) = \sum_{k=0}^{N} \hat{u}_{k}^{(1)} T_{k}(x)
$$

where, using the above expression for  $T'_{k}(x)$ , we obtain the expansion coefficients as

$$
\hat{u}_k^{(1)} = \frac{2}{c_k} \sum_{\substack{p=k+1 \ (p+k) \text{ odd}}}^N p \hat{u}_p, \quad k = 0, \dots, N-1, \quad \text{and} \quad \hat{u}_N^{(1)} = 0
$$

 $\triangleright$  Spectral differentiation (with the expansion coefficients as unknowns) can thus be written as

$$
\hat{U}^{(1)}=\hat{\mathbb{D}}\hat{U},
$$

where  $\hat{U} = [\hat{\mathbf{\iota}}_0 \, \ldots, \hat{\mathbf{\iota}}_N]^{\mathsf{T}}$  ,  $\hat{U}^{(1)} = [\hat{\mathbf{\iota}}_0^{(1)}]$  $\stackrel{(1)}{0} \cdots, \stackrel{(1)}{W}$  $\bigwedge^{(1)}$ ]<sup>T</sup>, and  $\hat{\mathbb{D}}$  is an upper-triangular matrix with entries deduced based on the previous expression

 $\blacktriangleright$  For the second derivative one obtains similarly

$$
u''_N(x) = \sum_{k=0}^N \hat{u}_k^{(2)} \mathcal{T}_k(x)
$$
  

$$
\hat{u}_k^{(2)} = \frac{1}{c_k} \sum_{\substack{p=k+2 \ (p+k) \text{ even}}}^N p(p^2 - k^2) \hat{u}_p, \quad k = 0, \dots, N-2
$$

and  $\hat{u}_{\textsf{N}}^{(2)}=\hat{u}_{\textsf{N}-1}^{(2)}=0$ 

 $\triangleright$  QUESTION — What is the structure of the second-order differentiation matrix?

Assume the function  $u(x)$  is approximated in terms of its nodal values, i.e.,  $\overline{M}$ 

$$
u(x) \cong u_N(x) = \sum_{j=0}^N u(x_j) C_j(x),
$$

where  $\{x_j\}$  are the  $\rm GAUSS\text{-}LOBATTO\text{-}CHEBYSHEV$  points and  $\mathcal{C}_j(x)$ are the associated CARDINAL FUNCTIONS

$$
C_j(x) = (-1)^{j+1} \frac{(1-x^2)}{c_j N^2(x-x_j)} \frac{d T_N(x)}{dx} = \frac{2}{Np_j} \sum_{m=0}^N \frac{1}{p_m} T_m(x_j) T_m(x),
$$

where

$$
p_j = \begin{cases} 2 & \text{for } j = 0, N, \\ 1 & \text{for } j = 1, \dots, N-1 \end{cases}, \qquad c_j = \begin{cases} 2 & \text{for } j = N, \\ 1 & \text{for } j = 0, \dots, N-1 \end{cases}
$$

 $\blacktriangleright$  The DIFFERENTIATION MATRIX  $\mathbb{D}^{(p)}$  relating the nodal values of the *p*-th derivative  $u_{N}^{(p)}$  $N^{(P)}$  to the nodal values of *u* is obtained by differentiating the cardinal function appropriate number of times

<span id="page-13-0"></span>
$$
u_N^{(p)}(x_j) = \sum_{k=0}^N \frac{d^{(p)}C_k(x_j)}{dx^{(p)}} u(x_k) = \sum_{k=0}^N d_{jk}^{(p)} u(x_k), \ \ j=0,\ldots,N
$$

Expressions for the entries of the DIFFERENTIATION MATRIX  $d_{ik}^{(1)}$ jk at the the GAUSS-LOBATTO-CHEBYSHEV collocation points

$$
d_{jk}^{(1)} = \frac{\overline{c}_j}{\overline{c}_k} \frac{(-1)^{j+k}}{x_j - x_k}, \qquad 0 \le j, k \le N, j \ne k,
$$
  

$$
d_{jj}^{(1)} = -\frac{x_j}{2(1 - x_j^2)}, \qquad 1 \le j \le N - 1,
$$
  

$$
d_{00}^{(1)} = -d_{NN}^{(1)} = \frac{2N^2 + 1}{6},
$$

- $\blacktriangleright$  Thus in the matrix (operator) notation  $U^{(1)}=\mathbb{D} U$
- $\triangleright$  Note that ROWS of the differentiation matrix  $\mathbb D$  are in fact equivalent to N-th order asymmetric finite-difference formulas on a nonuniform grid; in other words, spectral differentiation using nodal values as unknowns is equivalent to finite differences employing  $ALL$  N GRID points available

Expressions for the entries of SECOND-ORDER DIFFERENTIATION  $\rm{MATRIX}$   $d^{(2)}_{jk}$  at the the  $\rm{Gauss\text{-}LOBATTO\text{-}CHEBYSHEV}$  collocation points  $(\mathit{U}^{(2)}=\mathbb{D}^{(2)}\mathit{U})$ 

$$
d_{jk}^{(2)} = \frac{(-1)^{j+k}}{\overline{c}_k} \frac{x_j^2 + x_j x_k - 2}{(1 - x_j^2)(x_j - x_k)^2},
$$
  
\n
$$
d_{jj}^{(2)} = -\frac{(N^2 - 1)(1 - x_j^2) + 3}{3(1 - x_j^2)^2},
$$
  
\n
$$
d_{0k}^{(2)} = \frac{2}{3} \frac{(-1)^k}{\overline{c}_k} \frac{(2N^2 + 1)(1 - x_k) - 6}{(1 - x_k)^2},
$$
  
\n
$$
1 \le j \le N - 1,
$$
  
\n
$$
d_{0k}^{(2)} = \frac{2}{3} \frac{(-1)^{N+k}}{\overline{c}_k} \frac{(2N^2 + 1)(1 + x_k) - 6}{(1 + x_k)^2},
$$
  
\n
$$
1 \le k \le N
$$
  
\n
$$
d_{0k}^{(2)} = \frac{2}{3} \frac{(-1)^{N+k}}{\overline{c}_k} \frac{(2N^2 + 1)(1 + x_k) - 6}{(1 + x_k)^2},
$$
  
\n
$$
0 \le k \le N - 1
$$
  
\n
$$
d_{00}^{(2)} = d_{NN}^{(2)} = \frac{N^4 - 1}{15},
$$

- Note that  $j^{(2)}_{jk}=\sum_{p=0}^{\mathsf{N}}d^{(1)}_{jp}d^{(1)}_{pk}$ pk
- Interestingly,  $\mathbb{D}^2$  is not a SYMMETRIC MATRIX ...

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 $\triangleright$  Consider an ELLIPTIC BOUNDARY VALUE PROBLEM  $(BVP)$ 

$$
- \nu u'' + au' + bu = f,
$$
  
\n
$$
\alpha_{-}u + \beta_{-}u' = g_{-}
$$
  
\n
$$
\alpha_{+}u + \beta_{+}u' = g_{+}
$$
  
\n
$$
x = 1
$$
  
\n
$$
x = 1
$$

- $\triangleright$  Chebyshev polynomials do not satisfy homogeneous boundary conditions, hence standard Galerkin approach is not directly applicable.
- **BASIS RECOMBINATION:** 
	- $\triangleright$  Convert the BVP to the corresponding form with  $HOMOGENEOUS$ boundary conditions
	- $\triangleright$  Take linear combinations of Chebyshev polynomials to construct a new basis satisfying HOMOGENEOUS DIRICHLET BOUNDARY CONDITIONS  $\varphi_k (\pm 1) = 0$

<span id="page-16-0"></span>
$$
\varphi_k(x) = \begin{cases} T_k(x) - T_0(x) = T_k - 1, & k - \text{even} \\ T_k(x) - T_1(x), & k - \text{odd} \end{cases}
$$

Note that the new basis preserves orthogonality

- $\triangleright$  THE TAU METHOD (Lanczos, 1938) consists in using a Galerkin approach in which explicit enforcement of the boundary conditions replaces projections on some of the test functions
- $\blacktriangleright$  Consider the residual

$$
R_N(x)=-\nu u_N''+au_N'+bu_N-f,
$$

where  $u_N(x) = \sum_{k=0}^{N} \hat{u}_k \, T_k(x)$ 

 $\triangleright$  Cancel projections of the residual on the first  $N-2$  basis functions

$$
(R_N, T_l)_{\omega} = \sum_{k=0}^N \left( -\nu \hat{u}_k^{(2)} + a \hat{u}_k^{(1)} + b \hat{u}_k \right) \int_{-1}^1 T_k T_l \omega \, dx - \int_{-1}^1 f T_l \omega \, dx, \quad l = 0, \ldots, N-2
$$

 $\blacktriangleright$  Thus, using orthogonality, we obtain

<span id="page-17-0"></span>
$$
-\nu \hat{u}_k^{(2)} + a \hat{u}_k^{(1)} + b \hat{u}_k = \hat{f}_k, \quad k = 0, \ldots, N-2
$$

where  $\hat{f}_k = \int_{-1}^{1} f \; \mathcal{T}_k \, \omega \, d\mathsf{x}$ 

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► Noting that 
$$
T_k(\pm 1) = (\pm 1)^k
$$
 and  $T'_k(\pm 1) = (\pm 1)^{k+1}k^2$ , the  
\n**BOUNDARY CONDITIONS** are enforced by supplementary the residual  
\nequations with  
\n
$$
\sum_{n=0}^{N} (-1)^k (\alpha_{-} - \beta_{-} k^2) \hat{u}_k = g_{-}
$$

$$
\sum_{k=0}^{\infty} (-1)^k (\alpha_- - \beta_- k^2) \hat{u}_k = g_-
$$
  

$$
\sum_{k=0}^N (-1)^k (\alpha_+ + \beta_+ k^2) \hat{u}_k = g_+
$$

Expressing  $\hat{u}_k^{(2)}$  $\hat{u}_k^{(2)}$  and  $\hat{u}_k^{(1)}$  $\hat{k}^{(1)}$  in terms of  $\hat{u}_k$  via the Chebyshev spectral differentiation matrices we obtain the following system

$$
\mathbb{A}\hat{U}=\hat{\digamma}
$$

where  $\hat{U}=[\hat{\mathbf{\iota}}_0,\ldots,\hat{\mathbf{\iota}}_N]^{\mathsf{T}}$  ,  $\mathsf{\mathit{F}}=[\hat{f}_0,\ldots,\hat{f}_{N-2},g_{-},g_{+}]$  and the matrix A is obtained by adding the two rows representing the boundary conditions (see above) to the matrix  $A_1 = -\nu \hat{D}^2 + a\hat{D} + bI$ .

 $\triangleright$  When the domain boundary is not just a point (e.g., in 2D / 3D), formulation of the Tau method becomes somewhat more involved

B. Protas [MATH745, Fall 2018](#page-0-0)

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 $\triangleright$  Consider the residual

$$
R_N(x)=-\nu u_N''+au_N'+bu_N-f,
$$

where  $u_N(x) = \sum_{k=0}^{N} \hat{u}_k \, T_k(x)$ 

 $\triangleright$  Cancel this residual at  $N-1$  GAUSS-LOBATTO-CHEBYSHEV collocation points located in the interior of the domain

$$
-\nu u''_N(x_j) + au'_N(x_j) + bu_N(x_j) = f(x_j), \ \ j = 1, \ldots, N-1
$$

 $\triangleright$  Enforce the two boundary conditions at endpoints

<span id="page-19-0"></span>
$$
\alpha_{-}u_{N}(x_{N})+\beta_{-}u'_{N}(x_{N})=g_{-}
$$

$$
\alpha_{+}u_{N}(x_{0})+\beta_{+}u'_{N}(x_{0})=g_{-}
$$

Note that this shows the utility of using the GAUSS-LOBATTO-CHEBYSHEV collocation points

 $\triangleright$  Consequently, the following system of  $N+1$  equations is obtained

$$
\sum_{k=0}^N(-\nu d_{jk}^{(2)}+ad_{jk}^{(1)})u_N(x_j)+bu_N(x_j)=f(x_j), \ \ j=1,\ldots,N-1
$$

$$
\alpha_{-}u_{N}(x_{N}) + \beta_{-}\sum_{k=0}^{N}d_{Nk}^{(1)}u_{N}(x_{k}) = g_{-}
$$
  

$$
\alpha_{+}u_{N}(x_{0}) + \beta_{+}\sum_{k=0}^{N}d_{0k}^{(1)}u_{N}(x_{k}) = g_{+}
$$

 $\ddot{\phantom{a}}$ 

which can be written as  $\mathbb{A}_{c}U = F$ , where  $[\mathbb{A}_{c}]_{ik} = [\mathbb{A}_{c0}]_{ik}$ ,  $j, k = 1, \ldots, N-1$  with  $\mathbb{A}_{c0}$  given by

$$
\mathbb{A}_{c0}=(-\nu\mathbb{D}^2+a\mathbb{D}+b\mathbb{I})U
$$

and the BOUNDARY CONDITIONS above added as the rows  $0$  and  $N$ of  $A_c$ 

 $\triangleright$  Note that the matrix corresponding to this system of equations may be POORLY CONDITIONED, so special care must be exercised when solving this system for large N.

Similar approach can be used when the nodal values  $u(x_i)$ , rather than the Chebyshev coefficients  $\hat{u}_k$  are unknowns

- When the equation has NONCONSTANT COEFFICIENTS, similar difficulties as in the Fourier case are encountered (evaluation of convolution sums )
- $\triangleright$  Consequently, the COLLOCATION (pseudo-spectral) approach is preferable along the guidelines laid out in the case of the Fourier spectral methods
- Assuming  $a = a(x)$  in the elliptic boundary value problem, we need to make the following modification to  $A_{c}$ :

$$
\mathbb{A}_{c0}' = (-\nu \mathbb{D}^2 + \mathbb{D}' + b\mathbb{I})U,
$$

where  $\mathbb{D}' = [a(x_j)d_{jk}^{(1)}]$ ,  $j,k = 1,\ldots,N$ 

► For the Burgers equation  $\partial_t u + \frac{1}{2}$  $\frac{1}{2}\partial_{x}u^{2}-\nu\partial_{x}^{2}u$  we obtain at every time step n

$$
(\mathbb{I}-\Delta t\,\nu\,\mathbb{D}^{(2)})U^{n+1}=U^n-\frac{1}{2}\Delta t\,\mathbb{D}\,W^n,
$$

where  $[W^n]_j = [U^n]_j [U^n]_j;$  Note that an algebraic system has to be solved at each time step

[Galerkin Approach & Basis Recombination](#page-16-0) [Galerkin Approach & Tau Method](#page-17-0) [Collocation Method](#page-19-0)

## Epilogue — Domain Decomposition

- $\blacktriangleright$  Motivation:
	- $\triangleright$  treatment of problem in IRREGULAR DOMAINS
	- $\triangleright$  stiff problems
- $\triangleright$  PHILOSOPHY partition the original domain  $\Omega$  into a number of  $_{\rm SUBDOMAINS}$   $\{\Omega_{m}\}_{m=1}^{M}$  and solve the problem separately on each those while respecting consistency conditions on the interfaces
- ▶ Spectral Element Method
	- $\triangleright$  consider a collection of problems posed on each subdomain Ω<sub>m</sub>  $\mathcal{L}u_{\infty} = f$

<span id="page-23-0"></span>
$$
u_{m-1}(a_m) = u_m(a_m), \qquad u_m(a_{m+1}) = u_{m+1}(a_{m+1})
$$

- $\triangleright$  Transform each subdomain Ω<sub>m</sub> to  $I = [-1, 1]$
- ightharpoonup is use a separate set of  $N_m$  or thogonal polynomials to approximate the solution on every subinterval
- $\triangleright$  boundary conditions on interfaces provide coupling between problems on subdomains