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- INTERPOLATION is a way of determining an expansion of a function μ in terms of some ORTHONORMAL BASIS FUNCTIONS alternative to Galerkin spectral projections
- ► Assuming that $S_N = \text{span}\{e^{i0k}, \ldots, e^{\pm iNx}\}$, we can determine an INTERPOLANT $v \in S_N$ of u, such that v coincides with u at $2N + 1$ points $\{x_i\}_{|i| \le N}$ defined by

$$
x_j = jh, \quad |j| \leq N, \quad \text{where} \quad h = \frac{2\pi}{2N+1}
$$

► For the interpolant we set $|v(x)=\sum_{|k|\leq N}a_ke^{ikx}$ where the coefficients a_k , $k = 1, \ldots, N$ can be determined by solving the algebraic system

$$
\sum_{|k|\leq N}e^{ikx_j} a_k=u(x_j), \quad |j|\leq N
$$

with the matrix $\mathbb{A}_{kj} = e^{ikx_j}, \quad k,j = -N, \ldots, N$

\blacktriangleright The system can be rewritten as

$$
\sum_{|k|\leq N} W^{jk} a_k = u(x_j), \quad |j| \leq N
$$

where $W=e^{ih}=e^{\frac{2i\pi}{2N+1}}$ is the principal root of order $(2N+1)$ of unity (since $W^{jk} = \left(e^{ih} \right)^{jk}$)

Theorem

The matrix $[\mathbb{W}]_{ik} = W^{jk}$ is unitary, i.e. $\mathbb{W}^T \overline{\mathbb{W}} = \mathbb{I}(2N+1)$

Proof.

Examine the expression

$$
\frac{1}{2N+1}\mathbb{W}^T\overline{\mathbb{W}} = \mathbb{I} \implies \frac{1}{2N+1}\sum_{|j|\leq N}W^{jk}W^{-jl} = \delta_{kl}
$$

If $k = 1$, then $W^{jk}W^{-jl} = W^{j(k-l)} = W^0 = 1$

 \blacktriangleright If $k\neq l$, define $\omega=W^{k-l}$, then

$$
\frac{1}{2N+1}\sum_{|j|\leq N}W^{jk}W^{-jl}=\frac{1}{2N+1}\sum_{|j|\leq N}\omega^j=\frac{1}{M}\sum_{j'=0}^{M-1}\omega^{j'}
$$

where $M = 2N + 1$, $j' = j$ if $0 \le j \le N$ and $j' = j + M$ if $-N\leq j < 0$, so that $\omega^{j+M}=\omega^j$. The proof is completed by using the expression for the sum of a finite geometric series

$$
(1-\omega)\sum_{j'=0}^{M-1}\omega^{j'}=1-\omega^M=0.
$$

 \triangleright Since the matrix W is unitary and hence its INVERSE is given by its TRANSPOSE , the Fourier coefficients of the INTERPOLANT of μ in S_N can be calculated as follows:

$$
a_k = \frac{1}{2N+1} \sum_{|j| \leq N} z_j W^{-jk}, \text{ where } z_j = u(x_j)
$$

 \blacktriangleright The mapping

$$
\{z_j\}_{|j|\leq N}\longrightarrow \{a_k\}_{|k|\leq N}
$$

is referred to as DISCRETE FOURIER TRANSFORM (DFT)

- ► Straightforward evaluation of the expressions for a_k , $k = -N, \ldots, N$ (matrix–vector products) would result in the computational cost $\mathcal{O}(N^2)$; clever factorization of this operation, known as the $\overline{\text{FAST}}$ FOURIER TRANSFORMS (FFT), reduces this cost down to $\mathcal{O}(N \log(N))$
- \triangleright See www.fftw.org for one of the best publicly available implementations of the FFT.

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 \blacktriangleright Let $P_C: \: C^0_\rho(I) \to S_N \:$ be the mapping which associates with u its interpolant $v \in S_N$. Let $(\cdot, \cdot)_N$ be the GAUSSIAN QUADRATURE approximation of the inner product (\cdot, \cdot)

$$
(u,v)=\int_{-\pi}^{\pi}u\overline{v}\,dx\cong\frac{1}{2N+1}\sum_{|j|\leq N}u(x_j)\overline{v(x_j)}\triangleq(u,v)_N
$$

 \triangleright By construction, the operator P_C satisfies:

$$
(P_C u)(x_j) = u(x_j), \quad |j| \leq N
$$

and therefore also (orthogonality of the defect to S_N)

$$
(u-P_{C}u,v_{N})_{N}=0, \ \forall v_{N}\in S_{N}
$$

 \blacktriangleright By the definition of P_N we have

$$
(u-P_Nu,v_N)=0, \quad \forall v_N \in S_N
$$

► Thus, $P_C u(x) = \sum_{k=-N}^{N} (u, e^{ikx})_N e^{ikx}$ can be obtained analogously to $P_N u(x) = \sum_{k=-N}^N (u,e^{ikx}) e^{ikx}$ by replacing the scalar product (\cdot,\cdot) with the DISCRETE SCALAR PRODUCT $(\cdot, \cdot)_N$

Corollary

Thus, the INTERPOLATION COEFFICIENTS a_k are equivalent to the FOURIER SPECTRAL COEFFICIENTS \hat{u}_k when the latter are evaluated using the GAUSSIAN QUADRATURES.

Theorem

The two scalar products coincide on S_N , i.e.

$$
(u_N,v_N)=(u_N,v_N)_N, \quad \forall u_N,v_N\in S_N,
$$

hence for $u \in S_N$, $\hat{u}_k = a_k$, $k = -N, \ldots, N$.

Proof.

Examine the numerical integration formula $\frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) dx \cong \frac{1}{2N+1} \sum_{|j| \leq N} f(x_j);$ then for every $f = \sum_{k=-N}^N \hat{u}_k e^{ikx} \in S_N$ we have

$$
\frac{1}{2\pi} \int_{-\pi}^{\pi} e^{ikx} dx = \frac{1}{2N+1} \sum_{|j| \le N} e^{ikx_j} = \frac{1}{2N+1} \sum_{|j| \le N} W^{jk} = \begin{cases} 1 & k = 0 \\ 0 & \text{otherwise} \end{cases}
$$

Thus, for the uniform distribution of x_j , the Gaussian (trapezoidal) formula is EXACT for $f \in S_N$.

 \Box

Relation between Fourier coefficients \hat{u}_k of a function $u(x)$ and Fourier coefficients a_k of its interpolant; assume that $u(x) \notin S_N$

$$
\hat{u}_k = \frac{1}{2\pi} \int_{-\pi}^{\pi} u \overline{W}_k dx, \qquad W_k(x) = e^{ikx}
$$

$$
a_k = \frac{1}{2N+1} \sum_{|j| \le N} u(x_j) \overline{W_k(x_j)}
$$

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Theorem For $u \in C^0_p(I)$ we have the relation

$$
a_k = \sum_{l \in \mathbb{Z}} \hat{u}_{k+lM}, \quad \text{where } M = 2N+1
$$

Proof. Consider the set of basis functions (in $L_2(I)$) $U_k = e^{ikx}$. We have:

$$
(U_k, U_n)_N = \frac{1}{2N+1} \sum_{|j| \le N} U_k(x_j) \overline{U_n(x_j)} = \frac{1}{2N+1} \sum_{|j| \le N} W^{j(k-n)} = \begin{cases} 1 & k = n \text{ (mod } M) \\ 0 & \text{otherwise} \end{cases}
$$

Since ${P}_{\mathcal{C}}u=\sum_{|j|\leq N}a_jW_j$, we infer from $({P}_{\mathcal{C}}u,{W}_k)_N=(u,{W}_k)_N$ that

$$
a_k = (P_Cu, W_k)_N = (u, W_k)_N = \left(\sum_{n \in \mathbb{Z}} \hat{u}_n W_n, W_k\right)_N = \sum_{n \in \mathbb{Z}} \hat{u}_n (W_n, W_k)_N = \sum_{l \in \mathbb{Z}} \hat{u}_{k+lM}
$$

□

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$$
\blacktriangleright
$$
 Thus

$$
u(x_j) = v(x_j) = \sum_{k=-\infty}^{\infty} \hat{u}_k e^{ikx_j} = \sum_{|k| \leq N} a_k e^{ikx_j} = \sum_{|k| \leq N} \left(\hat{u}_k + \sum_{l \in \mathbb{Z} \setminus \{0\}} \hat{u}_{k+lM} \right) e^{ikx_j}
$$

Corollary (Extremely Important Corollary Concerning Interpolation) two trigonometric polynomials e^{ik_1x} and e^{ik_2x} with different frequencies k_1 and k_2 are equal at the collocation points $x_j,~|j|\leq N$ when

 $k_2 - k_1 = l(2N + 1), \quad l = 0, \pm 1, \ldots$

Therefore, given a set of values at the collocation points x_j , $|j| \leq N$, it is impossible to distinguish between e^{ik_1x} and e^{ik_2x} . This phenomenon is referred to as ALIASING.

Note, however, that the modes appearing in the alias term correspond to frequencies larger than the cut–off frequency N.

Theorem (Error Estimates in $H_p^s(I)$)

Suppose $s \leq r$, $r > \frac{1}{2}$ $\frac{1}{2}$ are given, then there exists a constant C such that if $u \in H_p^r(I)$, we have

$$
||u - P_C u||_s \leq C(1 + N^2)^{\frac{s-r}{2}} ||u||_r
$$

Outline of the proof.

Note that P_C leaves S_N invariant, therefore $P_C P_N = P_N$ and we may thus write

$$
u-P_C u=u-P_N u+P_C(P_N-I)u
$$

Setting $w = (I - P_N)u$ and using the "triangle inequality" we obtain

$$
||u - P_C u||_s \le ||u - P_N u||_s + ||P_C w||_s
$$

► The term $||u - P_Nu||_s$ is upper–bounded using an earlier theorem

 \blacktriangleright Need to estimate $||P_Cw||_s$ — straightforward, but tedious ...

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- \triangleright Until now, we defined the Discrete Fourier Transform for an ODD number $(2N + 1)$ of grid points
- \triangleright FFT algorithms generally require an EVEN number of grid points
- \triangleright We can define the discrete transform for an EVEN number of grid points by constructing the interpolant in the space \tilde{S}_N for which we have dim $(\tilde{\mathcal{S}}_N) = 2N$. To do this we choose:

$$
\tilde{x}_j = j\tilde{h},
$$
\n $-N + 1 \leq j \leq N,$ \n $\tilde{h} = \frac{\pi}{N}$

- \triangleright All results presented before can be established in the case with 2N grid points with only minor modifications
- In However, now the N-th Fourier mode \hat{u}_N does not have its complex conjugate! This coefficient is usually set to zero $(\hat{u}_N = 0)$ to avoid an uncompensated imaginary contribution resulting from differentiation
- \triangleright ODD or EVEN collocation depending on whether $M = 2N + 1$ or $M = 2N$

- \triangleright Before we focused on representing the INTERPOLANT as a Fourier series $v(x_j) = \sum_{k=-N}^{N} a_k e^{ikx_j}$
- \triangleright Alternatively, we can represent the INTERPOLANT using the nodal values as (assuming, for the moment, infinite domain $x \in \mathbb{R}$)

$$
v(x)=\sum_{j=-\infty}^{\infty}u(x_j)C_j(x),
$$

where $C_i(x)$ is a CARDINAL FUNCTION with the property that $C_i(x_i) = \delta_{ii}$ (i.e., generalization of the LAGRANGE POLYNOMIAL for infinite domain)

In an infinite domain we have the WHITTAKER CARDINAL or $SINC$ function

$$
C_k(x) = \frac{\sin[\pi(x - kh)/h]}{\pi(x - kh)/h} = \text{sinc}[(x - kh)/h],
$$

where $\textsf{sinc}(x) = \frac{\textsf{sin}(\pi x)}{\pi x}$

Proof.

The Fourier transform of δ_{j0} is $\hat{\delta}(k) = h$ for all $k \in [-\pi/h, \pi/h]$; hence, the interpolant of δ_{j0} is $v(x) = \frac{h}{2\pi} \int_{-\pi/h}^{\pi/h} e^{ikx} \,dk = \frac{\sin(\pi x/h)}{\pi x/h}$ πx/h

- \triangleright Thus, the spectral interpolant of a function in an INFINITE domain is a linear combination of WHITTAKER CARDINAL functions
- \triangleright In a PERIODIC DOMAIN we still have the representation

$$
v(x) = \sum_{j=0}^{N-1} u(x_j) S_j(x),
$$

but now the C ARDINAL FUNCTIONS have the form

$$
S_j(x) = \frac{1}{N} \sin \left[\frac{N(x - x_j)}{2} \right] \cot \left[\frac{(x - x_j)}{2} \right]
$$

- \triangleright Proof similar to the previous (unbounded) case, except that now the interpolant in given by a $DISCRETE$ Fourier Transform
- \triangleright The relationship between the Cardinal Functions corresponding to the periodic and unbounded domains

$$
S_0(x) = \frac{1}{2N} \sin(Nx) \cot(x/2) = \sum_{m=-\infty}^{\infty} \text{sinc}\left(\frac{x - 2\pi m}{h}\right)
$$

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- \blacktriangleright Two ways to calculate the derivative $w(x_j) = u'(x_j)$ based on the values $\mathit{u}(\mathit{x}_j)$, where $0 \leq j \leq 2N+1$; denote $\mathit{U} = [\mathit{u}_0, \dots, \mathit{u}_{2N+1}]^{\mathit{T}}$ and $U' = [u'_0, \ldots, u'_{2N+1}]^T$
- \triangleright METHOD ONE approach based on differentiation in Fourier space:
	- ► calculate the vector of Fourier coefficients $\hat{U} = T\hat{U}$
	- **•** apply the diagonal differentiation matrix $\hat{U}' = \hat{D}\hat{U}$
	- \blacktriangleright return to real space via inverse Fourier transform $U = \mathbb{T}^{\mathcal{T}} \hat{U}$
- \triangleright REMARK formally we can write

$$
U' = \mathbb{T}^\mathcal{T} \hat{\mathbb{D}} \mathbb{T} U,
$$

however in practice matrix operations are replaced by FFTs

 \triangleright METHOD TWO — approach based on differentiation (in real space) of the interpolant $u'(x_j) = v'(x_j) = \sum_{j=0}^{N-1} u(x_j) S'_j(x)$, where the cardinal function has the following derivatives

$$
S'(x_j) = \begin{cases} 0, & j = 0 \ (mod \ N) \\ \frac{1}{2}(-1)^j \cot(jh/2), & j \neq 0 \ (mod \ N) \end{cases}
$$

 \triangleright Thus, since the interpolant is a linear combination of shifted Cardinal Functions, the differentiation matrix has the form of a TOEPLITZ circulant matrix

$$
\mathbb{D} = \begin{bmatrix}\n0 & -\frac{1}{2}\cot[(1h)/2] \\
-\frac{1}{2}\cot[(1h)/2] & \frac{1}{2}\cot[(2h)/2] \\
\frac{1}{2}\cot[(2h)/2] & -\frac{1}{2}\cot[(3h)/2] \\
-\frac{1}{2}\cot[(3h)/2] & \vdots \\
\frac{1}{2}\cot[(1h)/2] & \frac{1}{2}\cot[(1h)/2]\n\end{bmatrix}
$$

Higher–order derivatives obtained calculating $S^{(p)}(x_i)$ B. Protas [MATH745, Fall 2018](#page-0-0)

- \triangleright We are interested in a PARTIAL DIFFERENTIAL EQUATION (a boundary value problem) of the general form $\mathcal{L}u = f$
- \triangleright We will look for solutions in the form:

$$
u_N(x) = \sum_{\substack{|k| \leq N \\ 2N+1}} \hat{u}_k e^{ikx},
$$

=
$$
\sum_{j=1}^{2N+1} u(x_j) S_j(x),
$$

where $S_i(x)$ is the periodic cardinal function centered at x_i

- \triangleright For the above model problem we will analyze:
	- \blacktriangleright spectral Galerkin method
	- \blacktriangleright spectral Collocation method
		- ightharpoonup variant with the FOURIER COEFFICIENTS \hat{u}_k as the unknowns
		- ightharpoonup variant with the NODAL VALUES $u(x_i)$ as the unknowns

 \triangleright Consider the following 1D second–order elliptic problem in a periodic domain $Ω = [0, 2π]$

$$
\mathcal{L}u \triangleq \nu u'' - au' + bu = f,
$$

where ν , a and b are constant and $f = f(x)$ is a smooth 2π -periodic function.

For $\nu = 10$, $a = 1$, $b = 5$ and the RHS function

$$
f(x) = e^{\sin(x)} \left[\nu(\cos^2(x) - \sin(x)) - a\cos(x) + b \right]
$$

the solution is

$$
u(x)=e^{\sin(x)}
$$

For the GALERKIN approach we are interested in 2π -periodic solutions in the form

$$
u_N(x) = \sum_{|k| \leq N} \hat{u}_k e^{ikx}
$$

\triangleright RESIDUAL

$$
R_N(x) = \mathcal{L}u_N - f = \sum_{|k| \leq N} \hat{u}_k \mathcal{L} e^{ikx} - f
$$

 \triangleright Cancellation of the residual in the mean (setting the projections on the basis functions $W_n(x)=e^{inx}$ equal to zero)

$$
(R_N, W_n) = \sum_{k=-N}^{N} \hat{u}_k(\mathcal{L}e^{ikx}, e^{inx}) - (f, e^{inx}) = 0, \quad n = -N, \dots, N
$$

► Noting that $\mathcal{L}e^{ikx} = (-\nu k^2 - iak + b)e^{ikx} \triangleq \mathcal{G}_k e^{ikx}$ we obtain

$$
\sum_{k=-N}^{N} \mathcal{G}_k \hat{u}_k \int_0^{2\pi} e^{i(k-n)} dx = \hat{f}_n, \quad n = -N, \ldots, N
$$

Assuming $G_k \neq 0$, we obtain the GALERKIN EQUATIONS for \hat{u}_k

$$
\mathcal{G}_k \hat{u}_k = \hat{f}_k, \qquad k = -N, \ldots, N
$$

- \triangleright The Galerkin equations are DECOUPLED
- ► Since *u* is real, it is necessary to calculate \hat{u}_k for $k > 0$ only

 \triangleright RESIDUAL (with the expansion coefficients \hat{u}_k as unknowns)

$$
R_N(x) = \mathcal{L}u_N - f = \sum_{|k| \leq N} \hat{u}_k \mathcal{L} e^{ikx} - f
$$

 \blacktriangleright Cancelling the residual pointwise at the collocation points x_j , $i=1,\ldots,M$ \sum N k −−N $(\mathcal{G}_k \hat{u}_k - \tilde{f}_k)e^{ikx_j} = 0, \ \ j = 1, \ldots, M$

where (note the ALIASING ERROR) $\widetilde{f}_k = \widehat{f}_k + \sum_{l \in \mathbb{Z} \smallsetminus \{0\}} \widehat{f}_{k+l\mathsf{M}}$

 \triangleright Thus, the COLLOCATION EQUATIONS for the Fourier coefficients

$$
\mathcal{G}_k \hat{u}_k = \tilde{f}_k = \hat{f}_k + \sum_{l \in \mathbb{Z} \setminus \{0\}} \hat{f}_{k+lM}, \quad k = -N, \ldots, N
$$

- \triangleright Formally, the GALERKIN and COLLOCATION methods are DISTINCT
- In practice, the projection (f, e^{ikx}) is evaluated using FFT and therefore also involves aliasing errors. Therefore, for the present problem, the two approaches are NUMERICALLY EQUIVALENT.

RESIDUAL (with the nodal values $u_N(x_i)$, $j = 1, \ldots, M$, as unknowns)

$$
R_N(x) = \mathcal{L} u_N - f
$$

 \blacktriangleright Cancelling the residual pointwise at the collocation points x_j , $i=1,\ldots,M$

$$
[R_N(x_1),\ldots,R_N(x_M)]^T=\mathbb{L}U_N-F=(\nu\mathbb{D}_2-a\mathbb{D}_1+b\mathbb{I})U_N-F=0,
$$

where $U_N = [u_N(x_1), \ldots, u_N(x_M)]^T$ and \mathbb{D}_1 and \mathbb{D}_2 are the differentiation matrices.

 \triangleright Derivation of the DIFFERENTIATION MATRICES

u

$$
u_N^{(p)}(x_j) = \sum_k (ik)^p \hat{u}_k e^{ikx_j}
$$

$$
\hat{u}_k = \frac{1}{M} \sum_{j=1}^M u_N(x_j) e^{-ikx_j}
$$
 \implies
$$
u_N^{(p)}(x_i) = \sum_{j=1}^M d_{ij}^{(p)} u_N(x_j)
$$

 \triangleright Differentiation Matrices (for even collocation, i.e., $I_N = -N + 1, \ldots, N$ and $M = 2N$)

$$
d_{ij}^{(1)} = \begin{cases} \frac{1}{2}(-1)^{i+j} \cot(h_{ij}) & \text{if } i \neq j \\ 0 & \text{if } i = j \end{cases}, \ d_{ij}^{(2)} = \begin{cases} \frac{1}{4}(-1)^{i+j}N + \frac{(-1)^{i+j+1}}{2 \sin^2(h_{ij})} & \text{if } i \neq j \\ -\frac{(N-1)(N-2)}{12} & \text{if } i = j \end{cases}
$$

\blacktriangleright Remarks:

- \triangleright The differentiation matrices are full (and not so well–conditioned ...), so the system of equations for $u_N(x_i)$ is now COUPLED
- \triangleright For constant coefficient PDEs the present approach is therefore inferior to the first collocation approach with the Fourier coefficients used as unknowns
- \triangleright Note the relationship to the banded matrices obtained when approximating differential operators using finite differences
- \triangleright QUESTION Derive the above differentiation matrices, also for the case of odd collocation

Nyquist-Shannon Sampling Theorem

- \blacktriangleright If a periodic function $f(x)$ has a Fourier transform $\hat{f}_k=0$ for $|k| > M$, then it is completely determined by providing the function values at a series of points spaced $\Delta x = \frac{1}{2\Lambda}$ $\frac{1}{2M}$ apart. The values $f_n = f\left(\frac{n}{2\hbar}\right)$ $\frac{n}{2M}$) are called the SAMPLES OF $f(x)$.
- \triangleright The minimum sampling frequency that allows for reconstruction of the original signal, that is $2M$ samples per unit distance, is known as the $NyqUIST$ $FREQUENCY$. The time in between samples is called the NYQUIST INTERVAL.
- \triangleright The NYQUIST–SHANNON SAMPLING THEOREM is a fundamental tenet in the field of INFORMATION THEORY (originally formulated by Nyquist in 1928, but formally proved by Shannon only in 1949)